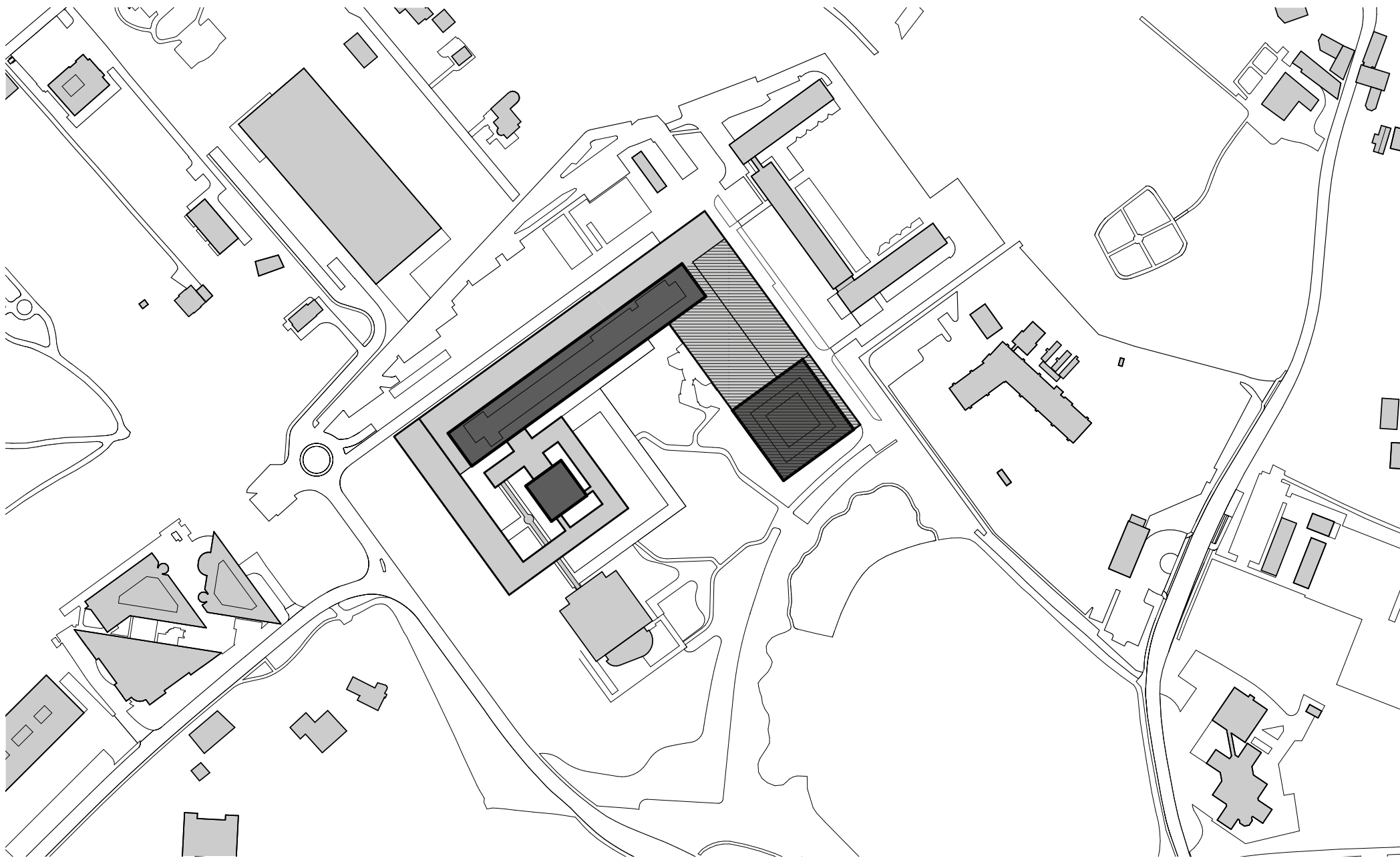




Plan de situation

0 10 20 50 100m

